Roll No. Total Pages: 03

BCA/M-20

1901

COMPUTER GRAPHICS BCA-363

Time : Three Hours] [Maximum Marks : 80

Note: Attempt *Five* questions in all, selecting *one* question from each Unit. Q. No. 1 is compulsory. All questions carry equal marks.

- 1. (a) Differentiate between interactive and passive computer graphics.
 - (b) Define affine transformation.
 - (c) What is Clipping? What is the relationship between clipping and windowing?
 - (d) Name different Cartesian co-ordinate reference frames.
 - (e) Name some common problems associated with scan conversion of elementary objects.
 - (f) What do you mean by color palette?
 - (g) Define Point Clipping.
 - (h) Write a short note on Rubber-Band techniques. **8**×2

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Unit I

- **2.** List the operating characteristics for the following display technologies :
 - (a) Raster refresh system
 - (b) Vector refresh system
 - (c) Plasma panels
 - (d) LCDs.

Also write some applications appropriate for each of these display technologies. 10,6

- 3. (a) Explain various popular graphics input devices.
 - (b) Explain the various applications areas of computer graphics. **8,8**

Unit II

- **4.** Write an algorithm to plot a line using Bresenham's method. How is it better than DDA?

 10,6
- 5. Explain scan conversion of an ellipse. Compare polynomial method and trigonometric method of scan conversion of an ellipse.4,12

Unit III

- 6. Derive clockwise and anticlockwise transformation matrices about the origin. Give a transformation matrix to rotate an object by 45° in anticlockwise direction and then to scale it in the horizontal direction by one-third of the original.

 10,6
- 7. (a) Define homogeneous coordinates. What are the advantages of homogeneous coordinates? 6
 - (b) What is Shearing? Is it possible to shear an object by scaling and rotation only? Describe. 5
 - (c) What is raster transformation? Where is raster transformation used?

Unit IV

- 8. Can a line clipping algorithm be used for clipping a polygon? Justify your answer.Explain the Sutherland-Hodgman polygon clipping algorithm.6,10
- 9. (a) Explain composite transformation with reference to3-D coordinate system.
 - (b) Derive rotation transformation matrix to rotate a 3-dimensional object about an arbitrary axis with angle θ .